

Crank-Nicholson (to solve $u_t = u_{xx}$) $k = \text{time step}$ $h = \text{space step}$

$$\frac{U_i^{n+1} - U_i^n}{k} = \frac{1}{2} \left(\frac{U_{i-1}^n - 2U_i^n + U_{i+1}^n}{h^2} \right) + \frac{1}{2} \left(\frac{U_{i-1}^{n+1} - 2U_i^{n+1} + U_{i+1}^{n+1}}{h^2} \right)$$

Let $r = \frac{k}{2h^2}$, then

$$-r U_{i-1}^{n+1} + (1+2r) U_i^{n+1} - r U_{i+1}^{n+1} = r U_{i-1}^n + (1-2r) U_i^n + r U_{i+1}^n \quad 1 \leq i \leq M-1$$

$$U_0^{n+1} = g_0(t_{n+1}) \quad U_M^{n+1} = g_1(t_{n+1}) \quad g_0 \text{ and } g_1 \text{ are given}$$

This is an implicit method

Matrix form

$$\begin{bmatrix}
 (1+2r) & -r & 0 & \dots & \dots & \dots & 0 \\
 -r & (1+2r) & -r & \dots & \dots & \dots & \vdots \\
 0 & -r & (1+2r) & -r & \dots & \dots & 0 \\
 \vdots & \vdots & \vdots & \vdots & \ddots & \ddots & \vdots \\
 0 & \dots & \dots & 0 & -r & (1+2r)
 \end{bmatrix}
 \begin{bmatrix}
 U_1^{n+1} \\
 \vdots \\
 U_{M-1}^{n+1}
 \end{bmatrix}
 =
 \begin{bmatrix}
 r [g_0(t_n) + g_0(t_{n+1})] + (1-2r) U_1^n + r U_2^n \\
 \vdots \\
 r U_{M-2}^n + (1-2r) U_{M-1}^n + r (g_1(t_n) + g_1(t_{n+1}))
 \end{bmatrix}$$

positive definite symmetric matrix, banded with bandwidth 1

use Cholesky

Local truncation errors

Def: The local truncation error is obtained by inserting the exact solution $u(x,t)$ of the PDE into the scheme and determine

by how much it fails to satisfy the discrete equations.

Method 1

$$\tau(x,t) = \frac{u(x,t+k) - u(x,t)}{k} - \frac{1}{h^2} [u(x-h,t) - 2u(x,t) + u(x+h,t)]$$

↑
truncation error

$$u(x,t+k) \approx u(x,t) + u_t(x,t)k + \frac{1}{2} u_{tt}(x,t)k^2$$

$$u(x-h,t) \approx u(x,t) - u_x(x,t)h + \frac{1}{2} u_{xx}(x,t)h^2 - \frac{1}{3!} u_{xxx}(x,t)h^3 + \frac{1}{4!} u_{xxxx}(x,t)h^4$$

$$u(x+h,t) \approx u(x,t) + u_x(x,t)h + \frac{1}{2} u_{xx}(x,t)h^2 + \frac{1}{3!} u_{xxx}(x,t)h^3 + \frac{1}{4!} u_{xxxx}(x,t)h^4$$

$$\tau(x,t) \approx \left(u_t(x,t) + \frac{1}{2} u_{tt}(x,t)k \right) - \left(u_{xx}(x,t) + \frac{1}{12} u_{xxxx}(x,t)h^2 \right)$$

Since u is a solution of the PDE, we have $u_t(x,t) = u_{xxx}(x,t)$

then $\boxed{u_{tt}(x,t) = u_{xxt}(x,t) = u_{xxxx}(x,t)}$

$$\tau(x,t) \approx u_{xxxx}(x,t) \left(\frac{k}{2} - \frac{h^2}{12} \right)$$

This method is of order $O(h^2 + k)$

Truncation error for Crank-Nicholson

$$\tau(x,t) = \frac{u(x,t+k) - u(x,t)}{k} - \frac{1}{2h^2} \left[u(x-h,t) - 2u(x,t) + u(x+h,t) \right] - \frac{1}{2h^2} \left[u(x-h,t+k) - 2u(x,t+k) + u(x+h,t+k) \right]$$

$$1 \quad \frac{u(x, t+k) - u(x, t)}{k} \approx u_t(x, t) + \frac{k}{2} u_{tt}(x, t) + \frac{k^2}{3!} u_{ttt}(x, t)$$

$$\frac{-1}{2} \quad \frac{u(x-h, t) - 2u(x, t) + u(x+h, t)}{h^2} \approx u_{xx}(x, t) + \frac{1}{12} u_{xxxx}(x, t) h^2$$

$$\frac{-1}{2} \quad \frac{u(x-h, t+k) - 2u(x, t+k) + u(x+h, t+k)}{h^2} \approx u_{xx}(x, t+k) + \frac{h^2}{12} u_{xxxx}(x, t+k)$$

$$\approx u_{xx}(x, t) + u_{xxt}(x, t)k + \frac{1}{2} u_{xxtt}(x, t)k^2 + \frac{1}{12} u_{xxxx}(x, t)h^2$$

$$\begin{aligned} \zeta(x, t) \approx & \left(u_t(x, t) + \frac{k}{2} u_{tt}(x, t) + \frac{k^2}{6} u_{ttt}(x, t) \right) - \frac{1}{2} \left(2u_{xx}(x, t) + \frac{h^2}{6} u_{xxxx}(x, t) \right. \\ & \left. + u_{xxt}(x, t)k + \frac{1}{2} u_{xxtt}(x, t)k^2 \right) \end{aligned}$$

Use $u_t(x,t) = u_{xx}(x,t)$ $u_{tt}(x,t) = u_{xxxx}(x,t)$

$u_{ttt}(x,t) = u_{xxxxx}(x,t)$ $u_{xxt}(x,t) = u_{xxxx}(x,t)$

$u_{xxtt}(x,t) = u_{xxxxxx}(x,t)$

$$\begin{aligned} \tau(x,t) \approx & \left(u_{xx} + \frac{h}{2} u_{xxxx} + \frac{h^2}{6} u_{xxxxxx} \right) - \frac{1}{2} \left(2u_{xx} + \frac{h^2}{6} u_{xxxx} + \right. \\ & \left. + h u_{xxxx} + \frac{1}{2} u_{xxxxxx} h^2 \right) = u_{xxxx} \left(-\frac{h^2}{12} \right) + u_{xxxxxx} \left(-\frac{h^2}{12} \right) \end{aligned}$$

$$= O(h^2 + h^2)$$

Von Neuman analysis

Method 1

$$U_i^{n+1} = U_i^n + \frac{k}{h^2} (U_{i-1}^n - 2U_i^n + U_{i+1}^n)$$

$$U_0^{n+1} = g_0(t_{n+1}) \quad U_M^{n+1} = g_1(t_{n+1})$$

$$U_i^0 = \eta(x_i)$$

Assume that because of machine precision or other sources of error, we have an error in the initial condition, i.e. we solve

$$\tilde{U}_i^{n+1} = \tilde{U}_i^n + \frac{k}{h^2} (\tilde{U}_{i-1}^n - 2\tilde{U}_i^n + \tilde{U}_{i+1}^n)$$

$$\tilde{U}_0^{n+1} = g_0(t_{n+1}) \quad \tilde{U}_M^{n+1} = g_1(t_{n+1})$$

$$\tilde{U}_i^0 = \eta(x_i) + \delta(x_i) \quad \text{with } \delta(x_i) \text{ small}$$

Assume all the rest of the calculations are exact.

$$\underbrace{U_i^n}_{\text{we compute}} = \underbrace{U_i^n}_{\text{we want}} + \underbrace{Z_i^n}_{\text{error}}$$

Z_i^n satisfies

$$Z_i^{n+1} = Z_i^n + \frac{k}{h^2} (Z_{i-1}^n - 2Z_i^n + Z_{i+1}^n)$$

$$Z_0^{n+1} = Z_M^{n+1} = 0$$

$$Z_i^0 = \delta(x_i)$$

Fact 1: $\begin{bmatrix} z_1^0 \\ \vdots \\ z_{M-1}^0 \end{bmatrix} \in \mathbb{R}^{M-1}$

$$V_1 = \begin{bmatrix} \sin\left(\frac{\pi}{M}\right) \\ \sin\left(\frac{\pi}{M} 2\right) \\ \vdots \\ \sin\left(\frac{\pi}{M} (M-1)\right) \end{bmatrix} \quad V_2 = \begin{bmatrix} \sin\left(2\frac{\pi}{M}\right) \\ \sin\left(2\frac{\pi}{M} 2\right) \\ \vdots \\ \sin\left(2\frac{\pi}{M} (M-1)\right) \end{bmatrix} \quad \dots \quad V_q = \begin{bmatrix} \sin\left(\frac{q\pi}{M}\right) \\ \sin\left(\frac{q\pi}{M} 2\right) \\ \vdots \\ \sin\left(\frac{q\pi}{M} (M-1)\right) \end{bmatrix}$$

$V_1, V_2, \dots, V_{M-1}$ are $M-1$ vectors in $\mathbb{R}^{M-1}$ THEY ARE LINEARLY INDEPENDENT