

Algorithm (to compute  $y[x_0, \dots, x_i]$ )

Input:  $x_i, y_i$

Output:  $y[x_0, \dots, x_i]$  in  $y_i$

for  $j = 1:n$

for  $i = n : j$

$$y_i = \frac{y_i - y_{i-1}}{x_i - x_{i-1}}$$

end

end

Complexity:  $(n-1) + (n-2) + \dots + 1 = \frac{n(n-1)}{2} = O(n^2)$

Obs:  $P(x) = y[x_0] + y[x_0, x_1](x-x_0) + \dots + y[x_0, \dots, x_n](x-x_0)\dots(x-x_{n-1})$

$$P(x) = \left( \left( y[x_0, \dots, x_n](x-x_{n-1}) + y[x_0, \dots, x_{n-1}] \right) (x-x_{n-2}) + y[x_0, \dots, x_{n-2}] \right) (x-x_{n-3})$$

Algorithm (to evaluate  $P(x)$ )

Input:  $y[x_0, \dots, x_n]$  in  $y_i$  and  $x_i$  and  $x$

Output:  $P(x)$  in  $p$

$$p = y_n$$

for  $i = n-1 : 1$

$$p = p(x - x_i) + y_i$$

end

Complexity =  $n-1 = O(n)$

Example  $f(x) = \frac{1}{1+25x^2} \quad -5 \leq x \leq 5$

$$x_i = -5 + i \quad 0 \leq i \leq 10 \quad y_i = f(x_i)$$

What went wrong?

- 1) Maybe choosing equidistant points is not that good
- 2) Maybe it is better to approximate the function by many different low degree polynomials. One in each little interval.  
First divide the whole interval in many small intervals.

Notation  $y_i = f(x_i) \quad y[x_0, \dots, x_n] = f[x_0, \dots, x_n]$

$P$  = polynomial of degree  $n$  that satisfies  $P(x_i) = y_i \quad 0 \leq i \leq n$

Goal: How big is  $f(x) - P(x)$  for  $x$  in  $\text{int}(x_0, \dots, x_n)$

$\text{int}(x_0, \dots, x_n) = (a, b)$  where  $a = \min\{x_i\}$   $b = \max\{x_i\}$

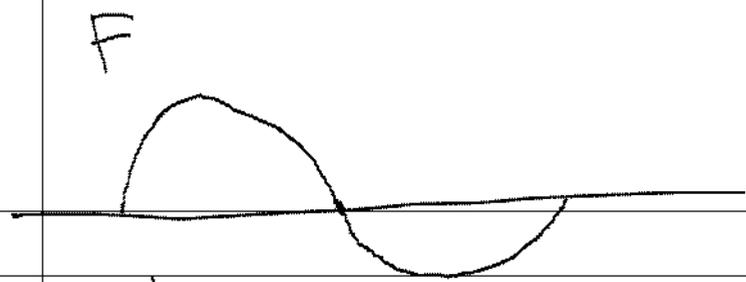
Obs: There exists  $\xi \in \text{int}(x_0, \dots, x_n)$  such that

$$f(x) - P(x) = \frac{f^{(n+1)}(\xi)}{(n+1)!} (x-x_0)(x-x_1)\dots(x-x_n)$$

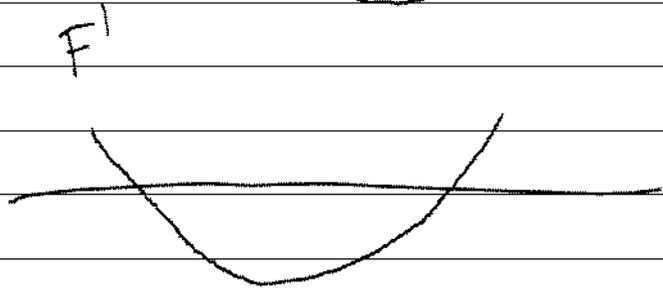
proof:  $\Phi(z) = (z-x_0)(z-x_1)\dots(z-x_n)$

$$G(z) = f(z) - P(z) - \frac{f(x) - P(x)}{\Phi(x)} \times \Phi(z)$$

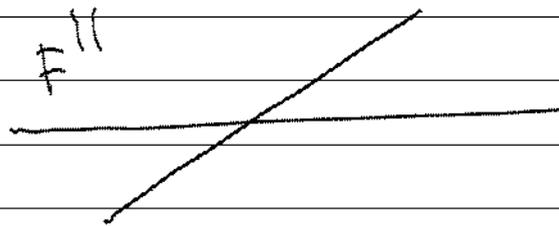
$G(z) = 0$  for  $z = x_0, x_1, \dots, x_n$  and also  $z = x$



If  $F$  has  $n+2$  zeros in  $(a, b)$   
 then  $F^{(n+1)}$  has a zero in  $(a, b)$



then, there exist  $\xi \in \text{int}(x_0, \dots, x_n)$  such  
 that  $G^{(n+1)}(\xi) = 0$



$$G^{(n+1)}(\xi) = f^{(n+1)}(\xi) - \underbrace{P^{(n+1)}(\xi)}_{=0} - \underbrace{\frac{f(x) - P(x)}{\Phi(x)}}_{\underbrace{\quad}_{(n+1)!}} = 0$$

$$f(x) - P(x) = \frac{f^{(n+1)}(\xi)}{(n+1)!} \Phi(x)$$

Obs:  $\Phi(x) = (x-x_0)(x-x_1)\dots(x-x_n)$

Goal: Given  $(a, b)$ , select  $x_0, x_1, \dots, x_n \in [a, b]$  so that

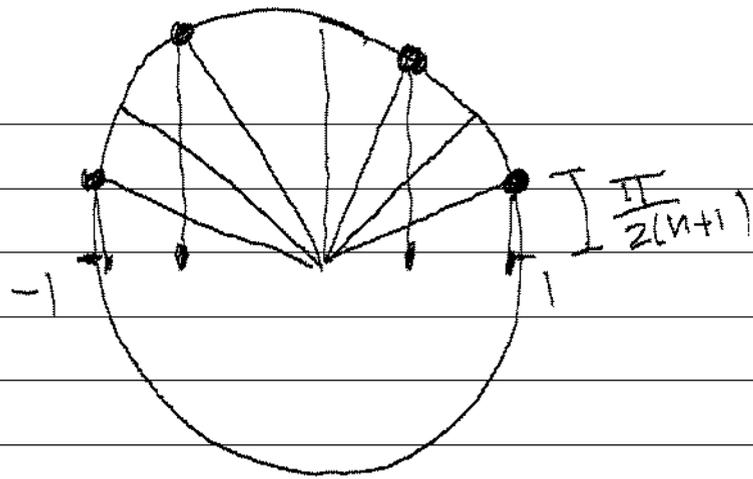
$\max_{x \in [a, b]} |\Phi(x)|$  is as small as possible

Notation  $\|\Phi\|_\infty = \max_{x \in [a, b]} |\Phi(x)|$

Obs: The points  $x_0, \dots, x_n$  that make  $\|\Phi\|_\infty$  as small as possible are the Tchebycheff points

$$x_k = \frac{(b-a)}{2} \cos \left[ \left( \frac{2(n-k)+1}{n+1} \right) \frac{\pi}{2} \right] + \frac{(a+b)}{2}$$

$$k = 0, \dots, n$$



## Splines

Obs: Approximating a function  $f$  over an interval  $[a, b]$  by a polynomial  $p$ , does not work very well always. It is better to split the interval  $[a, b]$  into  $n$  little intervals and approximate  $f$  by a different low degree polynomial in each little interval.

Def: Let  $a = x_0 < x_1 < \dots < x_n = b$ . A spline function of degree  $d$  with nodes at the points  $x_i$ ,  $i = 0, 1, \dots, n$  is a function  $s(x)$  with the properties

a) On each interval  $[x_{i-1}, x_i]$ ,  $s(x)$  is a polynomial of degree  $d$

b)  $s(x)$  and its first  $(d-1)$  derivatives are continuous in  $[a, b]$