

$$x' = Ax \quad A \in \mathbb{R}^{2 \times 2}$$

We need to find two solutions,  $x_1$  and  $x_2$ , such that  $x_1(0)$  and  $x_2(0)$  are linearly independent. Any other solution is a linear combination of  $x_1(0)$  and  $x_2(0)$ .

Case 1:  $A = \lambda I = \begin{bmatrix} \lambda & 0 \\ 0 & \lambda \end{bmatrix}$

$$\begin{aligned} x_1' &= \lambda x_1 \quad \longrightarrow \quad x_1 = c_1 e^{\lambda t} \\ x_2' &= \lambda x_2 \quad \longrightarrow \quad x_2 = c_2 e^{\lambda t} \end{aligned} \quad x = x(0) e^{\lambda t}$$

Obs: Let  $A \in \mathbb{R}^{2 \times 2}$ ,  $v \in \mathbb{R}^2$ ,  $\lambda \in \mathbb{R}$ .

If  $Av = \lambda v$  then  $x = v e^{\lambda t}$  is a solution.

of  $x' = Ax$

proof:  $x' = \begin{bmatrix} x_1' \\ x_2' \end{bmatrix} = \begin{bmatrix} \frac{d}{dt} v_1 e^{\lambda t} \\ \frac{d}{dt} v_2 e^{\lambda t} \end{bmatrix} = \begin{bmatrix} \lambda v_1 e^{\lambda t} \\ \lambda v_2 e^{\lambda t} \end{bmatrix}$

$$\begin{aligned} & \left[ \frac{d}{dt} v_2 e^{\lambda t} \right] = \lambda v_2 e^{\lambda t} \\ & = \lambda v e^{\lambda t} = \lambda x \end{aligned}$$

Example:  $A = \begin{bmatrix} 2 & 1 \\ 1 & 2 \end{bmatrix}$     $\lambda = 3$     $v = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$

$$x = v e^{\lambda t} = \begin{bmatrix} e^{3t} \\ e^{3t} \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \end{bmatrix} e^{3t}$$

$$x' = 3 \begin{bmatrix} 1 \\ 1 \end{bmatrix} e^{3t} = \begin{bmatrix} 2 & 1 \\ 1 & 2 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \end{bmatrix} e^{3t} = Ax \quad \checkmark$$

Back on solving  $x' = Ax$

Case 2:  $A$  has 2 different real eigenvalues  $\alpha$  and  $\beta$  with eigenvectors  $v$  and  $w$ .

$$Av = \alpha v \quad \text{and} \quad Aw = \beta w$$

From the last observation,  $x_1 = v e^{\alpha t}$  and  $x_2 = w e^{\beta t}$  are solutions of  $x' = Ax$ .

Since  $x_1(0) = v$  and  $x_2(0) = w$  are

eigenvectors of different eigenvalues,  
 then, they are linearly independent.  
 Thus,  $x$  is a solution of  $x' = Ax$   
 if and only if

$$x = c_1 v e^{\alpha t} + c_2 w e^{\beta t}$$

Example:  $x'_1 = 4x_1 - 2x_2$        $x_1(0) = 1$   
 $x'_2 = 3x_1 - x_2$        $x_2(0) = 2$

$$A = \begin{bmatrix} 4 & -2 \\ 3 & -1 \end{bmatrix}$$

$$\begin{aligned} P(A) &= \det \begin{bmatrix} 4-\lambda & -2 \\ 3 & -1-\lambda \end{bmatrix} = (4-\lambda)(-1-\lambda) + 6 = \\ &= \lambda^2 - 3\lambda + 2 = (\lambda-1)(\lambda-2) \end{aligned}$$

Eigenvectors  $\lambda_1 = 1$        $\begin{bmatrix} 3 & -2 \\ 3 & -2 \end{bmatrix}$        $v_1 = \begin{bmatrix} 2 \\ 3 \end{bmatrix}$

$\lambda_2 = 2$        $\begin{bmatrix} 2 & -2 \\ 3 & -1 \end{bmatrix}$        $w = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$

$$\boxed{\lambda_2 = 2} \quad \begin{bmatrix} 2 & -2 \\ 3 & -3 \end{bmatrix} \quad v_2 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$x = c_1 \begin{bmatrix} 2 \\ 3 \end{bmatrix} e^t + c_2 \begin{bmatrix} 1 \\ 1 \end{bmatrix} e^{2t}$$

Impose the initial conditions. Set  $t=0$

$$\begin{bmatrix} 1 \\ 2 \end{bmatrix} = c_1 \begin{bmatrix} 2 \\ 3 \end{bmatrix} + c_2 \begin{bmatrix} 1 \\ 1 \end{bmatrix} \quad \begin{array}{l} 1 = 2c_1 + c_2 \\ 2 = 3c_1 + c_2 \end{array}$$

$$c_1 = 1 \quad c_2 = -1$$

$$x = \begin{bmatrix} 2 \\ 3 \end{bmatrix} e^t - \begin{bmatrix} 1 \\ 1 \end{bmatrix} e^{2t}$$

$$x_1 = 2e^t - e^{2t}$$

$$x_2 = 3e^t - e^{2t}$$

Obs: Assume  $A$  has only one eigenvalue  $\lambda$  and  $A \neq \lambda I$ . Let  $v$  be an eigenvector. Let  $w$  be a solution of  $(A - \lambda I)w = v$ .

Then  $x = (w + tv) e^{\lambda t}$  is a solution of  $x' = Ax$

proof:  $x' = v e^{\lambda t} + \lambda(w + tv) e^{\lambda t}$

$$Ax = A(\omega + t\nu) e^{\lambda t} = (A\omega + \nu + t\lambda\nu) e^{\lambda t}$$

then  $x' = Ax \checkmark$  [auxiliary notes:

$$(A - \lambda I)\omega = \nu \text{ then } A\omega = \lambda\omega + \nu)$$

Case 3: A has only 1 eigenvalue  $\lambda$ .

$\nu$  is an eigenvector.  $\omega$  a solution of

$$(A - \lambda I)\omega = \nu. \text{ then } x' = Ax \Leftrightarrow$$

$$x = c_1 \nu e^{\lambda t} + c_2 (\omega + t\nu) e^{\lambda t}$$

for some  $c_1$  and  $c_2 \in \mathbb{R}$ .

Example:  $x_1' = 6x_1 - x_2$

$$x_2' = x_1 + 4x_2$$

$$A = \begin{bmatrix} 6 & -1 \\ 1 & 4 \end{bmatrix} \quad P(A) = \det \begin{bmatrix} 6-\lambda & -1 \\ 1 & 4-\lambda \end{bmatrix} =$$

$$= \lambda^2 - 10\lambda + 25 = (\lambda - 5)^2 \quad \lambda = 5$$

Eigenvector  $\boxed{\lambda = 5}$   $\begin{bmatrix} 1 & -1 \\ 1 & -1 \end{bmatrix} = A - 5I \quad \nu = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$

$$(A - 5I)w = v \quad \begin{bmatrix} 1 & -1 \\ 1 & -1 \end{bmatrix} \begin{bmatrix} w_1 \\ w_2 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \end{bmatrix} \quad w = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

$$x = c_1 \begin{bmatrix} 1 \\ 1 \end{bmatrix} e^{5t} + c_2 \left( \begin{bmatrix} 1 \\ 0 \end{bmatrix} + t \begin{bmatrix} 1 \\ 1 \end{bmatrix} \right) e^{5t}$$

$$x_1 = c_1 e^{5t} + c_2 (1+t) e^{5t}$$

$$x_2 = c_1 e^{5t} + c_2 t e^{5t}$$

## Complex valued functions

$$f(t) = f_1(t) + i f_2(t) \quad t, f_1(t) \& f_2(t) \text{ real}$$

$$\text{Ex: } f(t) = t + i e^t$$

$$\text{Def: } a, b \in \mathbb{R} \quad z = a + bi$$

$$e^z = e^{a+bi} = e^a (\cos b + i \sin b)$$

$$\text{Ex: } e^{i\pi} = e^0 (\cos \pi + i \sin \pi) = -1$$

$$e^{1+i\frac{\pi}{2}} = e (\cos \frac{\pi}{2} + i \sin \frac{\pi}{2}) = i e$$

Properties: 0)  $a \in \mathbb{R}$

$$e^{a+io} = e^a (\cos 0 + i \sin 0) e^a \quad \checkmark$$

$$1) e^{z_1+z_2} = e^{z_1} e^{z_2}$$

$$\text{Ex: } \lambda = a+bi, \quad a, b \in \mathbb{R}, \quad t \in \mathbb{R}$$

$$f(t) = e^{\lambda t} = e^{at+bt i} = e^{at} (\cos(bt) + i \sin(bt)) \\ = f_1(t) + i f_2(t)$$

$$\text{Re}(f(t)) = f_1(t) = e^{at} \cos(bt)$$

$$\text{Im}(f(t)) = f_2(t) = e^{at} \sin(bt)$$

Derivatives of complex valued functions

$$f(t) = f_1(t) + i f_2(t)$$

$$f'(t) = f_1'(t) + i f_2'(t)$$

$$\text{Ex: } \frac{d}{dt} (t + i t^2) = 1 + i 2t$$

$$\text{Ex: } \lambda = a+bi$$

$$\frac{d}{dt} (e^{\lambda t}) = \frac{d}{dt} (e^{at} \cos bt) + i \frac{d}{dt} (e^{at} \sin bt) =$$

$$\frac{d}{dt}(e^{\lambda t}) = \frac{d}{dt}(e^{at} \cos bt) + i \frac{d}{dt}(e^{at} \sin bt) =$$

$$= \lambda e^{\lambda t} \quad \checkmark$$

Obs:  $Av = \lambda v$ .  $A \in \mathbb{R}^{2 \times 2}$ ,  $\lambda \in \mathbb{C}$ ,  
 $v \in \mathbb{C}^2$ . Then  $x = v e^{\lambda t}$  is a solution  
of  $x' = Ax$

Example:  $x_1' = x_2$      $x_2' = -x_1$      $A = \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix}$

$$P(\lambda) = \det \begin{bmatrix} \lambda & 1 \\ -1 & \lambda \end{bmatrix} = \lambda^2 + 1 \quad \lambda = \pm i$$

$$(A - iI)v = 0 \quad \begin{bmatrix} -i & 1 \\ -1 & -i \end{bmatrix} \quad v = \begin{bmatrix} 1 \\ i \end{bmatrix}$$

$$x = v e^{\lambda t} = \begin{bmatrix} 1 \\ i \end{bmatrix} e^{it} \quad \begin{matrix} x_1 = e^{it} \\ x_2 = i e^{it} \end{matrix}$$

Check.  $x_1' = i e^{it} = x_2$

Check:  $x_1' = i e^{it} = x_2$   
 $x_2' = -e^{it} = -x_1$  ✓

Obs: If  $x$  is a complex solution of  $x' = Ax$ , then  $\text{Re}(x)$  and  $\text{Im}(x)$  are real solutions of  $x' = Ax$

proof:  $x = \text{Re}(x) + i \text{Im}(x)$

$$\frac{dx}{dt} = \frac{d}{dt} \text{Re}(x) + i \frac{d}{dt} \text{Im}(x)$$

$$Ax = A \text{Re}(x) + i A \text{Im}(x)$$

Example:  $x_1' = x_2$        $x = \begin{bmatrix} 1 \\ i \end{bmatrix} e^{it}$   
 $x_2' = -x_1$

$$x = \begin{bmatrix} 1 \\ i \end{bmatrix} e^{it} = \begin{bmatrix} e^{it} \\ i e^{it} \end{bmatrix} = \begin{bmatrix} \cos t + i \sin t \\ i(\cos t + i \sin t) \end{bmatrix} =$$

$$= \begin{bmatrix} \cos t + i \sin t \\ -\sin t + i \cos t \end{bmatrix}$$

$$= \begin{bmatrix} \cos t + i \sin t \\ -\sin t + i \cos t \end{bmatrix}$$

$$\operatorname{Re}(x) = \begin{bmatrix} \cos t \\ -\sin t \end{bmatrix} = y$$

$$y_1' = -\sin t = y_2$$

$$y_2' = -\cos t = -y_1 \quad \checkmark$$

$$\operatorname{Im}(x) = \begin{bmatrix} \sin t \\ \cos t \end{bmatrix} = z$$

$$z_1' = \cos t = z_2$$

$$z_2' = -\sin t = -z_1$$

Obs: Let  $A \in \mathbb{R}^{2 \times 2}$ . If  $v$  is an eigenvector of  $A$  with eigenvalue  $\lambda$ , and  $\lambda \notin \mathbb{R}$ , then  $\operatorname{Re}(v)$  and  $\operatorname{Im}(v)$  are linearly independent.

Example  $A = \begin{bmatrix} 1 & -1 \\ 1 & 1 \end{bmatrix}$

$$P(\lambda) = \det \begin{bmatrix} 1-\lambda & -1 \\ 1 & 1-\lambda \end{bmatrix} = (1-\lambda)^2 + 1 = 0 \Rightarrow \lambda = 1 \pm i$$

Eigenvector of  $\lambda = 1+i$   $A - (1+i)I = \begin{bmatrix} -i & -1 \\ 1 & -i \end{bmatrix}$

$$v = \begin{bmatrix} i \\ 1 \end{bmatrix} \quad \operatorname{Re}(v) = \begin{bmatrix} 0 \\ 1 \end{bmatrix}, \quad \operatorname{Im}(v) = \begin{bmatrix} 1 \\ 0 \end{bmatrix} \text{ are}$$

linearly independent.

Last case:  $x' = Ax$ .  $\lambda$  is an eigenvalue of  $A$  and  $\lambda \notin \mathbb{R}$ . Let  $v$  be an eigenvector of  $A$  with eigenvalue  $\lambda$ . Then  $x$  is a solution of  $x' = Ax$  if and only if,  $x$  is of the form

$$x = c_1 \operatorname{Re}(v e^{\lambda t}) + c_2 \operatorname{Im}(v e^{\lambda t})$$

for some  $c_1$  and  $c_2 \in \mathbb{R}$

Example Solve the IVP

$$x_1' = x_1 - x_2$$

$$x_1(0) = -1$$

$$x_2' = x_1 + x_2$$

$$x_2(0) = 2$$

$$A = \begin{bmatrix} 1 & -1 \\ 1 & 1 \end{bmatrix} \quad P(\lambda) = \det \begin{bmatrix} 1-\lambda & -1 \\ 1 & 1-\lambda \end{bmatrix} = (1-\lambda)^2 + 1$$

$$(\lambda-1)^2 + 1 = 0 \quad \lambda = 1 \pm i$$

$$\lambda = 1+i \quad A - (1+i)I = \begin{bmatrix} -i & -1 \\ 1 & -i \end{bmatrix} \quad v = \begin{bmatrix} i \\ 1 \end{bmatrix}$$

$$\begin{aligned}
 v e^{\lambda t} &= \begin{bmatrix} i \\ 1 \end{bmatrix} e^{(1+i)t} = \begin{bmatrix} i \\ 1 \end{bmatrix} e^t (\cos t + i \sin t) \\
 &= \begin{bmatrix} -e^t \sin t + i e^t \cos t \\ e^t \cos t + i e^t \sin t \end{bmatrix} = \begin{bmatrix} -e^t \sin t \\ e^t \cos t \end{bmatrix} + i \begin{bmatrix} e^t \cos t \\ e^t \sin t \end{bmatrix}
 \end{aligned}$$

$$x = c_1 e^t \begin{bmatrix} -\sin t \\ \cos t \end{bmatrix} + c_2 e^t \begin{bmatrix} \cos t \\ \sin t \end{bmatrix}$$

Replace  $t$  by 0 to get

$$\begin{bmatrix} -1 \\ 2 \end{bmatrix} = c_1 \begin{bmatrix} 0 \\ 1 \end{bmatrix} + c_2 \begin{bmatrix} 1 \\ 0 \end{bmatrix} \quad \begin{array}{l} c_1 = 2 \\ c_2 = -1 \end{array}$$

$$x = 2e^t \begin{bmatrix} -\sin t \\ \cos t \end{bmatrix} - e^t \begin{bmatrix} \cos t \\ \sin t \end{bmatrix}$$

$$x_1 = -2e^t \sin t - e^t \cos t$$

$$x_2 = 2e^t \cos t - e^t \sin t$$