

Def: V, W two vector spaces. $T: V \rightarrow W$ is a linear transformation if

$$T(f+g) = T(f) + T(g) \quad \text{for all } f, g \in V$$

$$\text{and } T(\lambda f) = \lambda T(f) \quad \text{for all } f \in V, \lambda \in \mathbb{R}.$$

$$\text{Im}(T) = \{ g \in W : g = T(f) \text{ for some } f \in V \}.$$

$$\text{Ker}(T) = \{ f \in V : T(f) = 0 \}$$

$$\text{rank}(T) = \dim(\text{Im}(T))$$

$$\text{nullity}(T) = \dim(\text{Ker}(T))$$

If $\dim V$ is finite. then

$$\dim(\text{Ker}(T)) + \dim(\text{Im}(T)) = \dim V$$

Examples 1) $C^\infty = \{ f: \mathbb{R} \rightarrow \mathbb{R} : \text{all the derivatives of } f \text{ exist} \}.$ $D: C^\infty \rightarrow C^\infty$

$$D(f) = f'$$

$$D(f+g) = (f+g)' = f' + g' = D(f) + D(g)$$

$$D(\lambda f) = (\lambda f)' = \lambda f' = \lambda D(f)$$

then D is a linear transformation.

$$\text{Ker}(D) = \{ f(x) = c \text{ for all } x \in \mathbb{R} \text{ for some } c \in \mathbb{R} \}$$

$$\text{Basis of } \text{Ker}(D) \quad \{1\} \quad \dim(\text{Ker}(D)) = 1$$

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$\text{Im}(D) = C^\infty$. If $f(x) \in C^\infty$, then $f(x) = D(\int_0^x f(t) dt)$

$$\dim(C^\infty) = \infty$$

If $\dim(C^\infty) < \infty$, then

$$\dim(C^\infty) = \underbrace{\dim(\text{Ker}(D))}_{=1} + \underbrace{\dim(\text{Im}(D))}_{\dim(C^\infty)}$$

$$2) C[0,1] = \{f: [0,1] \rightarrow \mathbb{R} : f \text{ is continuous}\}$$

$$I: C[0,1] \rightarrow \mathbb{R}$$

$$I(f) = \int_0^1 f(x) dx$$

$$I(f+g) = I(f) + I(g) \text{ \& } I(\lambda f) = \lambda I(f)$$

Def: V, W vector spaces. $T: V \rightarrow W$ linear transformation from V to W . We say that T is an isomorphism if $\text{Ker}(T) = \{0\}$ and $\text{Im}(T) = W$. This is the same, as saying that T is a bijection, i.e. one to one and onto. In this case, we say that V & W are isomorphic.

Obs: Let V be a vector space. Let $\{f_1, \dots, f_n\}$ be a basis of V . $B = \{f_1, \dots, f_n\}$. $L_B: V \rightarrow \mathbb{R}^n$.

$$L_B(f) = [f]_B. \quad L_B \text{ is an isomorphism.}$$

proof: $L_B(f+g) = [f+g]_B = [f]_B + [g]_B = L_B(f) + L_B(g)$

Recall $L_B(f) = \begin{bmatrix} c_1 \\ \vdots \\ c_n \end{bmatrix}$ if $f = c_1 f_1 + c_2 f_2 + \dots + c_n f_n$

$$L_B(\lambda f) = \lambda L_B(f)$$

$$L_B(f) = 0 \Rightarrow [f]_B = 0 \Rightarrow f = 0 \cdot f_1 + 0 \cdot f_2 + \dots + 0 \cdot f_n$$

then $f = 0$. then $\ker(L_B) = \{0\}$

Let $c = \begin{bmatrix} c_1 \\ \vdots \\ c_n \end{bmatrix} \in \mathbb{R}^n$ $L_B(c_1 f_1 + c_2 f_2 + \dots + c_n f_n) = \begin{bmatrix} c_1 \\ \vdots \\ c_n \end{bmatrix}$

then $\text{Im}(L_B) = \mathbb{R}^n$

Ex: $T: \mathbb{R}^{2 \times 2} \rightarrow \mathbb{R}^{2 \times 2}$ Let $S \in \mathbb{R}^{2 \times 2}$ invertible.

$T(A) = S^{-1}AS$. Show that T is a linear transformation

$$T(A+B) = S^{-1}(A+B)S = S^{-1}(AS + BS) = S^{-1}AS + S^{-1}BS = T(A) + T(B) \quad \checkmark$$

$$T(\lambda A) = S^{-1}(\lambda A)S = \lambda S^{-1}AS = \lambda T(A) \quad \checkmark$$

What is $\ker(T)$?

$$T(A) = 0 \quad S^{-1}AS = 0 \quad SS^{-1}AS = S0$$

$$AS = 0 \quad ASS^{-1} = 0S^{-1} \quad A = 0 \quad \checkmark$$

Then $\text{Ker}(T) = \{0\}$.

What is $\text{Im}(T)$? Claim $\text{Im}(T) = \mathbb{R}^{2 \times 2}$.

Let $B \in \mathbb{R}^{2 \times 2}$. Is $B = T(A)$ for some A ?

$$B = T(A) \quad B = S^{-1}AS \quad SBS^{-1} = A$$

$$B = T(SBS^{-1}) \quad \checkmark$$

Basis of $\mathbb{R}^{2 \times 2}$

$$A \in \mathbb{R}^{2 \times 2} \text{ then } A = \begin{bmatrix} a & b \\ c & d \end{bmatrix} = a \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} + b \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} + c \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix} + d \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}$$

$$\text{then } \mathbb{R}^{2 \times 2} = \text{Span} \left\{ \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} \right\}$$

Are $\begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}$ linearly independent? Yes because

$$a \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} + b \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} + c \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix} + d \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$$

$$\begin{bmatrix} a & b \\ c & d \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix} \text{ implies } \begin{matrix} a=0 & c=0 \\ b=0 & d=0 \end{matrix} \quad \checkmark$$

Theorem: $T: V \rightarrow W$ linear transformation. $\dim V$ and $\dim W$ are finite. then

- 1) V and W are isomorphic if and only if $\dim V = \dim W$
- 2) If $\ker(T) = \{0\}$ and $\dim V = \dim W$, then T is an isomorphism.
- 3) If $\operatorname{Im}(T) = W$ and $\dim V = \dim W$, then T is an isomorphism.

proof: 1) Assume $\dim V = \dim W = n$

Let $\{f_1, \dots, f_n\}$ be a basis of V

Let $\{g_1, \dots, g_n\}$ be a basis of W

$$T(f_i) = g_i \quad 1 \leq i \leq n.$$

$$f \in V, \text{ then } f = c_1 f_1 + \dots + c_n f_n$$

$$T(f) = c_1 T(f_1) + \dots + c_n T(f_n) = c_1 g_1 + \dots + c_n g_n$$

Claim T is linear transformation.

$$\text{Let } f, h \in V. \quad f = c_1 f_1 + \dots + c_n f_n$$

$$h = d_1 f_1 + \dots + d_n f_n$$

$$f+h = (c_1+d_1)f_1 + \dots + (c_n+d_n)f_n$$

$$\text{Then } T(f) = c_1 g_1 + \dots + c_n g_n$$

$$T(h) = d_1 g_1 + \dots + d_n g_n$$

$$T(f+h) = (c_1+d_1)g_1 + \dots + (c_n+d_n)g_n = T(f) + T(h).$$

$$\text{Similarly } T(\lambda f) = \lambda T(f)$$

$$T(f) = 0 \quad \text{implies} \quad c_1 g_1 + \dots + c_n g_n = 0$$

Since $\{g_1, \dots, g_n\}$ is a basis, then $c_1 = \dots = c_n = 0$.
 Then $f = c_1 f_1 + \dots + c_n f_n = 0$ Thus $\ker(T) = \{0\}$
 Is $\text{Im}(T) = W$? Let $g \in W$. $g = c_1 g_1 + \dots + c_n g_n$
 $g = T(c_1 f_1 + \dots + c_n f_n)$. Then $\text{Im}(T) = W$.

Matrix of a linear transformation

Ex: $P_2 = \{ \text{polynomials of degree 2 or less or polynomial 0} \}$

$$P_2 = \{ ax^2 + bx + c : a, b, c \in \mathbb{R} \}$$

$$\text{Basis of } P_2 = \{1, x, x^2\}$$

$$T: P_2 \rightarrow P_2$$

$$T(f) = f' + f'' \quad f' = \text{derivative of } f.$$

$$f = ax^2 + bx + c \text{ then } f' = 2ax + b$$

T is a linear transformation.

$$B = \{x^2, x, 1\} \text{ a basis of } V = P_2$$

Let $S: \mathbb{R}^n \rightarrow \mathbb{R}^n$ $n=3$ in this case. In general
 $n = \dim V$.

$$\begin{array}{ccc}
 P_2 & \xrightarrow{T} & P_2 \\
 \downarrow L_B & \uparrow L_B^{-1} & \downarrow L_B \\
 \mathbb{R}^3 & \xrightarrow{L_B^{-1} T L_B} & \mathbb{R}^3
 \end{array}$$

L_B is an isomorphism.
 L_B is a linear transformation

$L_B \downarrow \uparrow \begin{matrix} \xrightarrow{L_B^{-1}} \\ \xrightarrow{T} \\ \xrightarrow{L_B} \end{matrix} \downarrow L_B$
 $\mathbb{R}^3 \xrightarrow{S} \mathbb{R}^3$
 L_B is a linear transformation that is one-to-one and onto

$$S = L_B T L_B^{-1} : \mathbb{R}^3 \longrightarrow \mathbb{R}^3$$

$$Sx = Bx.$$

$$\begin{aligned}
 S\left(\begin{bmatrix} a \\ b \\ c \end{bmatrix}\right) &= L_B T L_B^{-1}\left(\begin{bmatrix} a \\ b \\ c \end{bmatrix}\right) = L_B T(ax^2 + bx + c) = \\
 &= L_B(2ax + b + 2a) = \begin{bmatrix} 0 \\ 2a \\ 2a+b \end{bmatrix}
 \end{aligned}$$

$$S\left(\begin{bmatrix} a \\ b \\ c \end{bmatrix}\right) = \begin{bmatrix} 0 \\ 2a \\ 2a+b \end{bmatrix} = \begin{bmatrix} 0 & 0 & 0 \\ 2 & 0 & 0 \\ 2 & 1 & 0 \end{bmatrix} \begin{bmatrix} a \\ b \\ c \end{bmatrix} = B \begin{bmatrix} a \\ b \\ c \end{bmatrix}$$

Def: $T: V \longrightarrow V$. T linear transformation.

V vector space. $\dim V = n$. $B = \{f_1, \dots, f_n\}$ a basis

of V . $S = L_B T L_B^{-1} : \mathbb{R}^n \longrightarrow \mathbb{R}^n$. S is a linear transformation. $S(x) = Bx$ for all x in $\mathbb{R}^n$ and some matrix B . The matrix B is called the B -matrix of the transformation T .

$$m_1 \quad \forall f \in V \quad [T(f)]_B = B[f]_B$$

Obs: Let $f \in V$ $[T(f)]_{\mathcal{B}} = B [f]_{\mathcal{B}}$

$$\begin{array}{ccc} V & \xrightarrow{T} & V \\ \downarrow L_{\mathcal{B}} = [\]_{\mathcal{B}} & & \downarrow [\]_{\mathcal{B}} = L_{\mathcal{B}} \\ \mathbb{R}^n & \xrightarrow{B_{\mathcal{X}}} & \mathbb{R}^n \end{array}$$

Obs: The j th column of B is $(\mathcal{B} = \{f_1, \dots, f_n\})$

$$B e_j = B [f_j]_{\mathcal{B}} = [T(f_j)]_{\mathcal{B}}$$

$$B = \begin{bmatrix} [T(f_1)]_{\mathcal{B}} & [T(f_2)]_{\mathcal{B}} & \dots & [T(f_n)]_{\mathcal{B}} \end{bmatrix}$$

Ex: $T(M) = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} M - M \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} \quad T: \mathbb{R}^{2 \times 2} \rightarrow \mathbb{R}^{2 \times 2}$

$$\mathcal{B} = \left\{ \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} \right\}$$

Compute the $\mathcal{B}$ -matrix of T .

$$\begin{array}{ccc} \mathbb{R}^{2 \times 2} & \xrightarrow{T} & \mathbb{R}^{2 \times 2} \\ \downarrow L_{\mathcal{B}} & & \downarrow L_{\mathcal{B}} \\ \mathbb{R}^4 & \xrightarrow{\quad} & \mathbb{R}^4 \\ x & \longmapsto & Bx \end{array}$$

$$x \in \mathbb{R}^4$$

$$\begin{aligned} L_{\mathcal{B}}^{-1}(x) &= x_1 \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} + x_2 \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} + \\ &+ x_3 \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix} + x_4 \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} x_1 & x_2 \\ x_3 & x_4 \end{bmatrix} \end{aligned}$$

$$x \mapsto Bx$$

$$T(L_B^{-1}(x)) = T \begin{bmatrix} x_1 & x_2 \\ x_3 & x_4 \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} x_1 & x_2 \\ x_3 & x_4 \end{bmatrix} - \begin{bmatrix} x_1 & x_2 \\ x_3 & x_4 \end{bmatrix} \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}$$

$$= \begin{bmatrix} x_3 & x_4 \\ 0 & 0 \end{bmatrix} - \begin{bmatrix} 0 & x_1 \\ 0 & x_3 \end{bmatrix} = \begin{bmatrix} x_3 & x_4 - x_1 \\ 0 & -x_3 \end{bmatrix}$$

$$L_B(T(L_B^{-1}(x))) = L_B \left(\begin{bmatrix} x_3 & x_4 - x_1 \\ 0 & -x_3 \end{bmatrix} \right) = \begin{bmatrix} x_3 \\ x_4 - x_1 \\ 0 \\ -x_3 \end{bmatrix} =$$

$$= \underbrace{\begin{bmatrix} 0 & 0 & 1 & 0 \\ -1 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & -1 & 0 \end{bmatrix}}_B \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix}$$

Let V be a vector space. $\dim V = n$.

Let $B = \{f_1, \dots, f_n\}$ be a basis of V

Let $U = \{g_1, \dots, g_n\}$ be a basis of V

Let $f \in V$. Question: can we get $[f]_U$ if we have $[f]_B$?

$$V \xrightarrow{L_B} \mathbb{R}^n$$

$$f \xrightarrow{\quad} [f]_B$$

$$L_U(L_B^{-1}([f]_B)) = [f]_U$$

$$\begin{array}{ccc}
 V & \xrightarrow{\quad} & \mathbb{R}^n \\
 L_u \downarrow & \swarrow L_B^{-1} & \uparrow L_u \\
 \mathbb{R}^n & & \mathbb{R}^n
 \end{array}
 \quad
 \begin{array}{c}
 [f]_B \\
 \downarrow L_u \\
 [f]_u
 \end{array}
 \quad
 L_{u \circ L_B^{-1}} : \mathbb{R}^n \rightarrow \mathbb{R}^n$$

$$L_{u \circ L_B^{-1}}(x) = Sx$$

$S = S_{B \rightarrow u}$ the j th column of S is

$$S[e_j] = L_u(L_B^{-1}[e_j]) = L_u(f_j) = [f_j]_u$$

$$S = \begin{bmatrix} [f_1]_u & [f_2]_u & \cdots & [f_n]_u \end{bmatrix}$$

Example $V = \text{Span}\{e^x, e^{-x}\}$

$$\sinh(x) = \frac{e^x - e^{-x}}{2}$$

$$B = \{e^x, e^{-x}\}$$

$$\cosh(x) = \frac{e^x + e^{-x}}{2}$$

$$u = \{\sinh x, \cosh x\}$$

Compute $S_{B \rightarrow u} = S = \begin{bmatrix} [e^x]_u & [e^{-x}]_u \end{bmatrix}$

$$[e^x]_u = \begin{bmatrix} a \\ b \end{bmatrix}$$

$$a \sinh x + b \cosh x = e^x$$

$$U = [u]^{-1} [b] \quad u \sinh x + b \cosh x = c$$

$$x=0 \Rightarrow b=1$$

$$\text{take derivatives} \quad a \cosh x + \sinh x = e^x$$

$$\text{now set } x=0 \Rightarrow a=1$$

$$[e^{-x}]_u = \begin{bmatrix} c \\ d \end{bmatrix} \quad c \sinh x + d \cosh x = e^{-x}$$

$$x=0 \quad d=1$$

$$c \cosh x + d \sinh x = -e^{-x}$$

$$x=0 \quad c=-1$$

$$\begin{bmatrix} 1 & -1 \\ 1 & 1 \end{bmatrix} = S$$

Theorem: V subspace of $\mathbb{R}^n$. $\dim V = l \leq n$.

$$U = \{a_1, \dots, a_l\} \text{ basis of } V$$

$$B = \{b_1, \dots, b_l\} \text{ basis of } V$$

$$S = S_B \rightarrow U$$

$$S = \begin{bmatrix} [b_1]_u & [b_2]_u & \dots & [b_l]_u \end{bmatrix}$$

$$[a_1, \dots, a_l] [b_1]_u =$$

$$[a_1 \dots a_\ell] [b_1]_u =$$

$$[x]_u = \begin{bmatrix} c_1 \\ \vdots \\ c_\ell \end{bmatrix} \quad c_1 a_1 + \dots + c_\ell a_\ell = x$$

$$\begin{bmatrix} a_1 & a_2 & \dots & a_\ell \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \\ \vdots \\ c_\ell \end{bmatrix} = x$$

$$[x]_u$$

$$\begin{bmatrix} a_1 & \dots & a_\ell \end{bmatrix} [x]_u = x \quad \text{replace } x \text{ by } b_j$$

$$\begin{bmatrix} a_1 & \dots & a_\ell \end{bmatrix} [b_j]_u = b_j$$

$$\begin{bmatrix} a_1 & \dots & a_\ell \end{bmatrix} \underbrace{\begin{bmatrix} [b_1]_u & \dots & [b_\ell]_u \end{bmatrix}}_{S_{B \rightarrow u}} = \begin{bmatrix} b_1 & \dots & b_\ell \end{bmatrix}$$

$$\begin{bmatrix} a_1 & \dots & a_\ell \end{bmatrix} S_{B \rightarrow u} = \begin{bmatrix} b_1 & \dots & b_\ell \end{bmatrix}$$

$$u = \{a_1, \dots, a_\ell\}$$

$$B = \{b_1, \dots, b_\ell\}$$

$$U = \{a_1, \dots, a_e\}$$

$$B = \{b_1, \dots, b_e\}$$