

Product of matrices

Def: $A \in \mathbb{R}^{p \times n}$, $B \in \mathbb{R}^{k \times p}$. Let

$$T: \mathbb{R}^n \rightarrow \mathbb{R}^p \quad T(x) = Ax$$

$$S: \mathbb{R}^p \rightarrow \mathbb{R}^k \quad S(y) = By$$

BA is the matrix such that

$$(S \circ T)(x) = (BA)x$$

Obs: BA is defined if the number of columns of B equals the number of rows of A .

If $A \in \mathbb{R}^{p \times n}$ then, if $x \in \mathbb{R}^n$, $Ax \in \mathbb{R}^p$

If we can do $B(Ax)$ and $Ax \in \mathbb{R}^p$, then

$$B \in \mathbb{R}^{k \times p}$$

$$\begin{matrix} B & A \\ \in & \in \\ \mathbb{R}^{k \times p} & \mathbb{R}^{p \times n} \end{matrix}$$

Obs. the i th column of $(BA)e_j$

$$e_j = \begin{bmatrix} 0 \\ \vdots \\ 1 \\ \vdots \\ 0 \end{bmatrix} \leftarrow j^{\text{th}}$$

Obs: the j^{th} column of $(BA)e_j$ $e_j = \begin{bmatrix} \vdots \\ 0 \end{bmatrix}$

$$(BA)e_j = B(Ae_j) = Ba_j$$

a_j is the j^{th} column of A

$$A = [a_1 \ a_2 \ \dots \ a_n]$$

$$BA = [Ba_1 \ Ba_2 \ \dots \ Ba_n]$$

$$\text{Obs: } B = \begin{bmatrix} b_1^T \\ \vdots \\ b_k^T \end{bmatrix} \quad x = \begin{bmatrix} b_1^T x \\ b_2^T x \\ \vdots \\ b_k^T x \end{bmatrix} = \begin{bmatrix} b_1 \cdot x \\ b_2 \cdot x \\ \vdots \\ b_k \cdot x \end{bmatrix}$$

$$BA = \begin{bmatrix} \text{---} \\ \text{---} \\ \text{---} \\ \text{---} \end{bmatrix} \begin{bmatrix} \text{---} \\ \text{---} \\ \text{---} \\ \text{---} \end{bmatrix} =$$

B j^{th}
 A

$$\begin{bmatrix} \text{---} \\ \text{---} \\ \text{---} \\ \text{---} \end{bmatrix} \begin{bmatrix} \text{---} \\ \text{---} \\ \text{---} \\ \text{---} \end{bmatrix}$$

i^{th} i^{th}

L jth

Ex: $\begin{bmatrix} 2 & -1 & 0 \\ 1 & 0 & 3 \\ -1 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 2 & 1 \\ 0 & -2 & 3 \\ -1 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 2(1) + (-1)(0) + 0(-1) \\ 1(1) + 0(0) + 3(-1) \\ 6 & -1 \\ 2 & 4 \end{bmatrix} =$

$= \begin{bmatrix} 2 & 6 & -1 \\ -2 & 2 & 4 \end{bmatrix}$

Obs Multiplication of matrices is not commutative,
in general $AB \neq BA$

Obs: $I = \begin{bmatrix} 1 & 0 & \dots & 0 \\ 0 & 1 & & \\ \vdots & & \ddots & \\ 0 & \dots & 0 & 1 \end{bmatrix} = [e_1, e_2, \dots, e_n] \in \mathbb{R}^{n \times n}$

$AI = [Ae_1, Ae_2, \dots, Ae_n] = [a_1, a_2, \dots, a_n] = A$

$Ix = \begin{bmatrix} e_1^T \\ e_2^T \\ \vdots \\ e_n^T \end{bmatrix} x = \begin{bmatrix} e_1 \cdot x \\ e_2 \cdot x \\ \vdots \\ e_n \cdot x \end{bmatrix} = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} = x$

$I \in \mathbb{R}^{n \times n}$

$x \in \mathbb{R}^n$

$\begin{bmatrix} 1 & 0 & \dots & 0 \\ 0 & 1 & & \\ \vdots & & \ddots & \\ 0 & \dots & 0 & 1 \end{bmatrix} = I$

$$I \in \mathbb{R}^{n \times n} \quad \bar{x}'' \in \mathbb{R}^n$$

$$I A = [I a_1 \quad I a_2 \quad \dots \quad I a_n] = [a_1 \quad a_2 \quad \dots \quad a_n] = A$$

Obs: $(AB)C = A(BC)$? yes

$$\begin{aligned} A x &= T(x) & ((AB)C)z &= ((T \circ S) \circ R)(z) = \\ B y &= S(y) & &= (T \circ S)(R(z)) = T(S(R(z))) = \\ C z &= R(z) & &= T((S \circ R)(z)) = (T \circ (S \circ R))(z) = \\ & & & (A(BC))z \end{aligned}$$

Thus $(AB)C = A(BC)$.

Obs: $A(C+D) = AC + AD$

$$(A+B)C = AC + BC$$

$$(\lambda A)B = A(\lambda B) = \lambda(AB)$$

We finished 2.3

Inverse of linear transformations and

matrices

Def: $f: X \rightarrow Y$. f has an inverse if for all $y \in Y$ there exists a unique $x \in X$ such that $f(x) = y$. the inverse of f is denoted by f^{-1} . $f^{-1}: Y \rightarrow X$

$f^{-1}(y) = x$ if and only if $f(x) = y$

Obs: $f(f^{-1}(y)) = y$

$$f^{-1}(f(x)) = x$$

$$(f^{-1})^{-1} = f$$

Obs: $T(x) = Ax$ $A \in \mathbb{R}^{k \times n}$

When is T invertible? (this means it has an inverse)

$Ax = b$ needs to have only one solution for all b

$[A | b]$ there are no free variables

$$\text{rank } A = n \leq k$$

later we will show that T^{-1} is also a linear transformation $T^{-1}: \mathbb{R}^k \rightarrow \mathbb{R}^n$

then $k \leq n$.

Obs: Let $A \in \mathbb{R}^{n \times n}$. The following are equivalent:

1) $T(x) = Ax$ is invertible

2) $\text{rank}(A) = n$

3) $\text{rref}(A) = I$

4) $Ax = b$ has a unique solution for

all $b \in \mathbb{R}^n$

5) $Ax = 0$ has $x = 0$ as the unique solution

Obs: $T(x) = Ax$ invertible. Then

$T^{-1}: \mathbb{R}^n \rightarrow \mathbb{R}^n$ is also a linear trans.

formation.

1) Let $x, y \in \mathbb{R}^n$

$$T^{-1}(x+y) = v \Rightarrow T(v) = x+y$$

$$T^{-1}(x) + T^{-1}(y) = w \Rightarrow T(w) = T(T^{-1}(x) + T^{-1}(y)) =$$

$$= T(T^{-1}(x)) + T(T^{-1}(y)) = x + y$$

then $T(v) = T(w)$, since T is invertible $\Rightarrow$

T is one to one, thus $v = w$, thus

$$T^{-1}(x+y) = T^{-1}(x) + T^{-1}(y)$$

Similarly, we can show that $T^{-1}(\lambda x) = \lambda T^{-1}(x)$

Thus, T^{-1} is a linear transformation.

$$T^{-1}(x) = Bx \quad \text{for some } B \in \mathbb{R}^{n \times n}$$

This B is called the inverse of A , where $T(x) = Ax$
and B is denoted by A^{-1}

Obs: $\begin{pmatrix} T^{-1} & T \\ 0 & 1 \end{pmatrix} (x) = x$

$$(A^{-1}A)x = Ix$$

thus $A^{-1}A = I$. Similarly, $AA^{-1} = I$

Def: $A \in \mathbb{R}^{n \times n}$. 1) A is invertible if

$T(x) = Ax$ is invertible.

2) The inverse of A is A^{-1} . $T^{-1}(x) = A^{-1}x$.

Obs: Let $A \in \mathbb{R}^{n \times n}$. A is invertible $\Leftrightarrow$

there exist $B \in \mathbb{R}^{n \times n}$ such that $AB = BA = I$.

In this case, this $B = A^{-1}$

Computing A^{-1} :

$$\text{Let } B = A^{-1} = [b_1 \ b_2 \ \dots \ b_n]$$

$$AB = I$$

$$A b_j = e_j$$

$[A \mid e_1 \ e_2 \ \dots \ e_n]$ do Gaussian elimination to
find RREF of this augmented matrix

Case 1. No free variables $\text{rank } A = n$. The RREF is $[I \mid b_1 \ b_2 \ \dots \ b_n]$

$$\text{Then } A^{-1} = [b_1 \ b_2 \ \dots \ b_n]$$

Case 2. Some free variables, then $\text{rank } A < n$, then A does not have an inverse.